

### APPLIED INVERSE PROBLEMS CONFERENCE

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# Realistic simulated MR data (virtual phantoms) and the development of IP algorithms

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Simulated data are essential for the

- > development,
- testing, and
- comparisons

of **data evaluation algorithms** for inverse problems of all kinds.

Ok, but WHY do we need to SIMULATE? Are there not enough real data?

#### First group of answers: Software developer's discomfort with «real» data

- ➤To acquire "real" signals one needs "real" samples which might bring forth the limits of the tested algorithm. Which is often not simple, unless the data are already available.
- ➢One also needs costly real instruments to generate real signals.
  Which is even harder and sometimes completely ruled out.
- Acquisition of "real" signals is often very slow compared to the rate with which one can generate simulated data.
- ➤ "Real" samples are almost always poorly characterized.
- "Real" samples often exhibit unexpected real-life complications which shift the focus from the algorithm to the sample itself.

#### Field-Cycling NMR (FFC or sample-shuffling)



#### What about FC of multi-component samples?

When we intend only a **small number k of discrete components** that are distinguishable in the decays  $S(\tau, B_{rlx})$ , then this is not really a new idea. Yet it is **a bit problematic** and **very time consuming**, so it is **rarely done**.



#### Second group of answers: Speeding up the development of a new algorithm

- Usually (though not always), generation of simulated data is very fast. This is particularly important when the tested algorithm needs to be numerically validated in terms of its bias and/or noise propagation, using Monte Carlo techniques.
- Simulated signals are more flexible in setting sample/acquisition parameters, adding well defined random noise, etc.
- ➤When there exists a good expert knowledge, simulated data can be made sophisticated enough to include precisely controlled amounts of typical artefacts encountered in experimental data. It is then possible to test to which extent is an algorithm robust with respect to such artefacts.

#### Examples of typical LR-NMR artefacts and problems:

#### ≻Noise (low S/N ratio).

#### Simulating realistic data is quite an art

But without simulating, how can you trust your algorithms with real data?

#### Examples of CPMG artefacts:



Note: the above are 1982 edu data (before PC's), but the «modern» real data are sometimes just as bad!

#### Examples of typical HR-NMR (spectroscopy) artefacts:



You thought that spectroscopy was better off then relaxometry??? Hehehehe !!!

#### Third group of answers

#### Comparing the relative performance of two or more algorithms

- Real-world algorithms are often aimed at applications of fuzzy nature and/or mathematically ill-defined ones. In such cases, even the end Users, when presented with several algorithms, are often unable to tell which one is the best. More objective methods than User satisfaction (such as benchmark data sets) are needed.
- Training data sets build from "real" data are often burdened by errors of human evaluators. Even infrequent errors in such data sets can have very deleterious effects on long-term development of algorithms.

Hence, realistically simulated benchmark sets, as well as training sets are often preferable to "real" data.

#### A particular study case: Inverse Laplace Transform of simulated decays (examples using the UPEN algorithm)



#### Three relaxation components with equal weights



#### Six relaxation components with the same weights



 $\leftarrow$ 

Ten different runs simulated adding always 0.16% of noise (just the blue trace has 0% noise)

Better relative resolution for long  $T_1$ 's, even though tau-values are distributed logarithmically!

Four runs simulated adding 0%, 1%, 3% and 9% noise

 $\rightarrow$ 



#### Algorithms performance testing should:

≻Be automated.

➢ Use well-known and standardized benchmark data sets, preferably simulated, and agreed upon by the whole community.

We call those virtual phantoms

#### What I did not tell you $\ensuremath{\mathfrak{S}}$

I have originally planned to present much more but, given the limited time, I could not.

- ➤Hybrid data, generated from an experimental data set by adding various artefacts and other features, are also of great interest.
- ➢In particular, iterated evaluations repeated on a hybrid set obtained by adding increasing amounts of noise (the method of controlled noise addition) allow in some cases back-extrapolate the results to a zero-noise situation.
- Detailed illustrations of most of the artefact-related concepts had to skipped and will appear in a subsequent publication.

Example of hybrid data used to test a novel PcBc algorithm (concurrent phase and baseline correction)



#### Conclusions

- Every software developer needs a fast generator of simulated data that is objective and independent of his algorithms.
- ➢It is desirable to be able to simulate data that include various artefacts. This requires a considerably deep practical knowledge of the experimental methodology.
- ➤When developing a data-processing algorithm, one should first construct suitable simulated benchmark data sets (for algorithm validation), and simulated training data set (for algorithm tuning).
- ➢ Fast and realistic generation of simulated data and their various uses is an emerging, self-standing Science.

Extra Byte develops commissioned data simulation tools and/or benchmark/training data sets for various NMR Relaxometry and NMR Spectroscopy tasks.

## Thank you for your attention!



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